

# Technology and applications of virtual 3D models using mobile mapping and 3D games engines

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## Process, what is new?

- Accurate photorealistic 3D model created with mobile mapping, semi-automatic processing, and put into 3D game engine
  - Construction of the ROAMER
  - Processing of the accurate photorealistic 3D model
  - Implementation in 3D game engine
  - Development of applications: integration of virtual and physical worlds
- Very close to what Navteq/Google/Microsoft can do in a large scale



# What is possible?



One man doing the whole process



## FGI ROAMER

### Characteristics

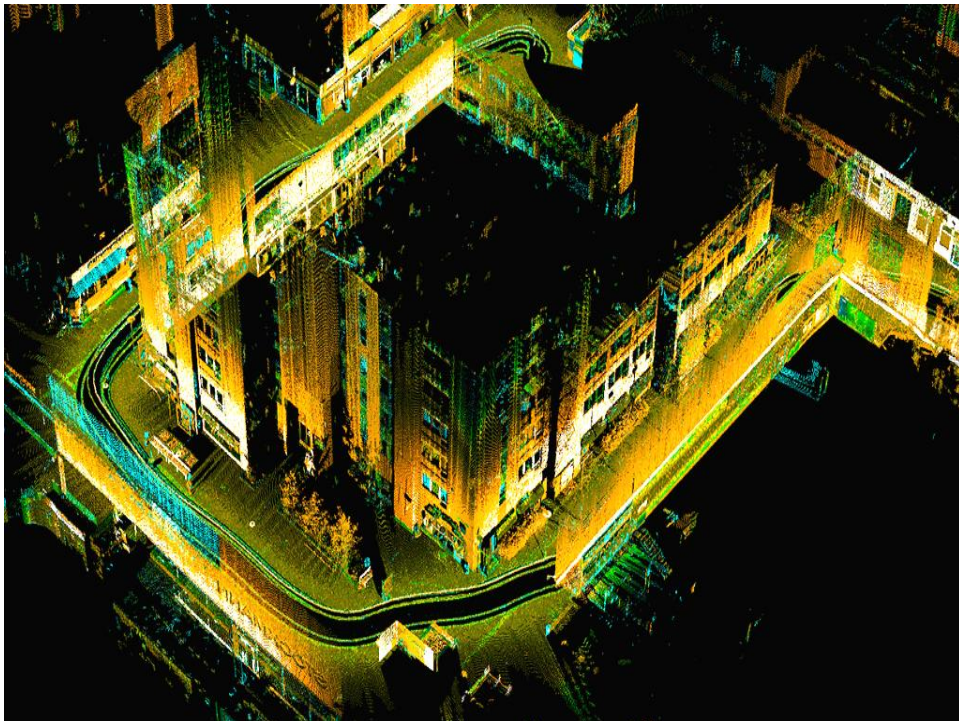
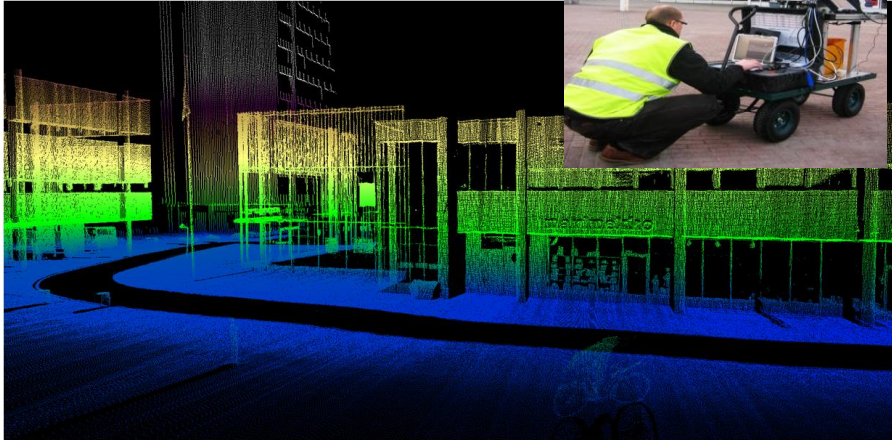
- Navigation solution 100 Hz
- Bi-trigger synchronization – laser and images
- 120-976 000 points / second
- 3-61 profiles/second
- 150 m corridor width
- Multiple scanner positions
- Multi-platform capability



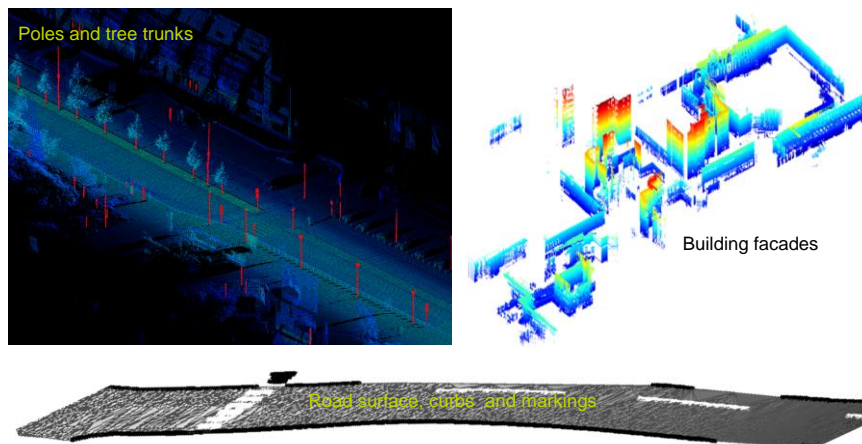
Kukko, A., Andrei, C.-O., Salminen, V.-M., Kaartinen, H., Chen, Y., Rönholm, P., Hyypä, H., Hyypä, J., Chen, R., Haggrén, H., Kosonen, I. and K. Čapek, 2007. Road environment mapping system of the Finnish Geodetic Institute - FGI ROAMER. In: *International Archives of Photogrammetry, Remote Sensing and Spatial Information Sciences* 36, Part 3/W52  
 Kaasalainen, S., Kaartinen, H., Kukko, A., Anttila, K. and A. Krooks, 2010. Brief Communication: Application of Mobile Laser Scanning in Snow Cover Profiling. *The Cryosphere* 5: 135–138  
 Aho, P., Kukko, A., Hyypä, H., Kaartinen, H., Hyypä, J. and A. Jaakkola, 2009. Application of boat-based laser scanning for river survey. *Earth Surface Processes and Landforms* 34: 1831-1838



# Data Acquisition



## Automatic processing of MLS data



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 Lehtomäki, M., Jaakkola, A., Hyypä, J., Kukko, A. and H. Kaartinen, 2010. Detection of Vertical Pole-Like Objects in a Road Environment Using Vehicle-Based Laser Scanning Data. *Remote Sens.* 2010, 2(3): 641-664  
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## Photorealistic 3D Model





## Low data amount – Details visible



## Game Engine Interface

